

Craig Robotics Solution Manual

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5. Let $B \cdot P_1 = B \cdot P_0 + 5 \, B \cdot V_0 = [9.5 \, 1.00 - 1.50]T$. The object's position in $\{A\}$ is $T \, B \, A \, P_1 = A \, B \, T \, P_1 = [-4.89 \, 2.11 \, 3.60]$ 6. $(2.1) \, R = \text{rot}(\hat{Y}, \varphi) \, \text{rot}(\hat{Z}, \theta) \, c\varphi \, 0 \, s\varphi = 0 \, 1 \, 0 \, -s\varphi \, 0 \, \dots$

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Introduction to Robotics - Sharif
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